

Gait training robot for neurological injuries

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# Gait Training Therapy



Manual Therapy

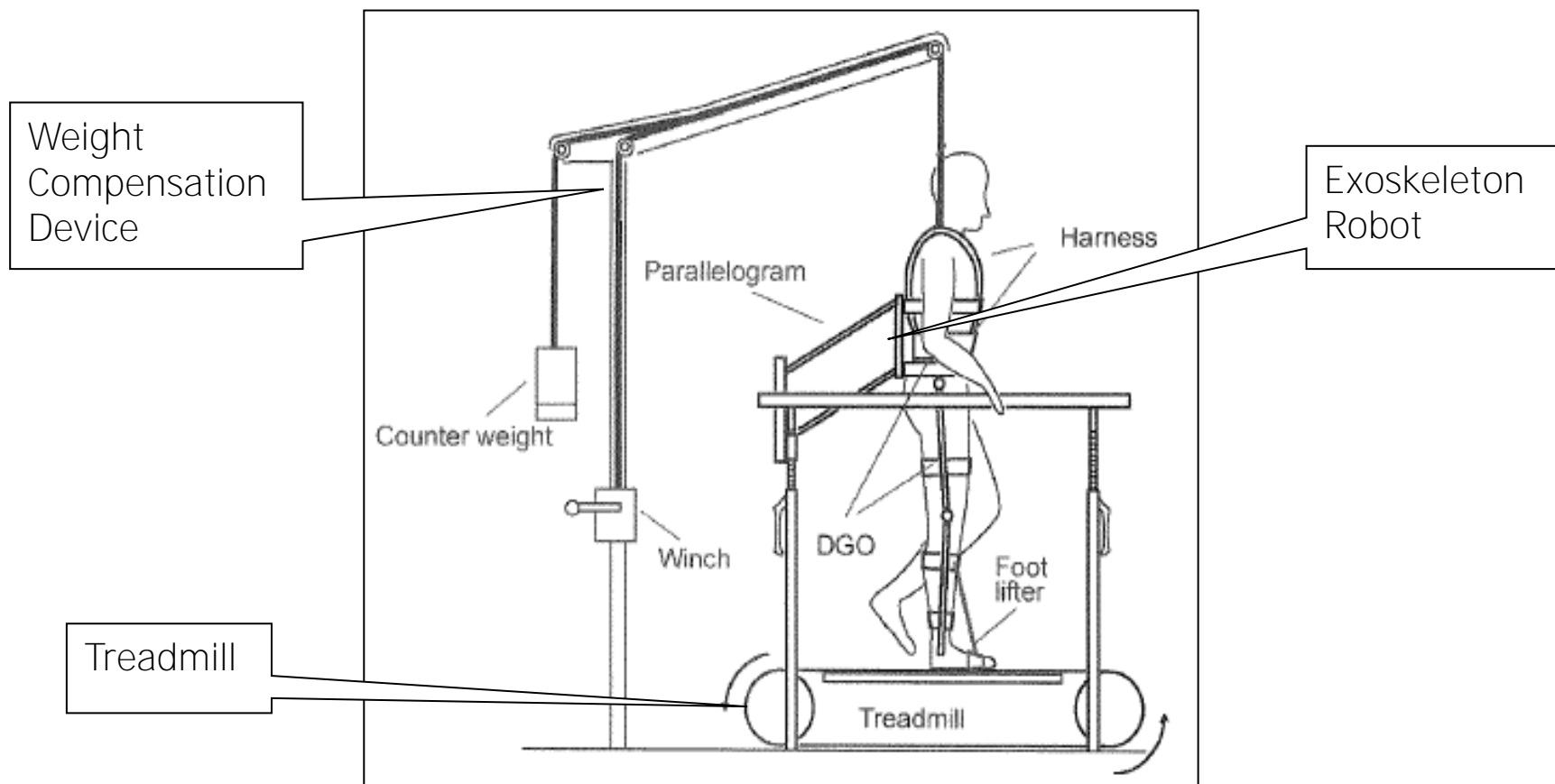
- Labor intensive



Robot Assisted Therapy

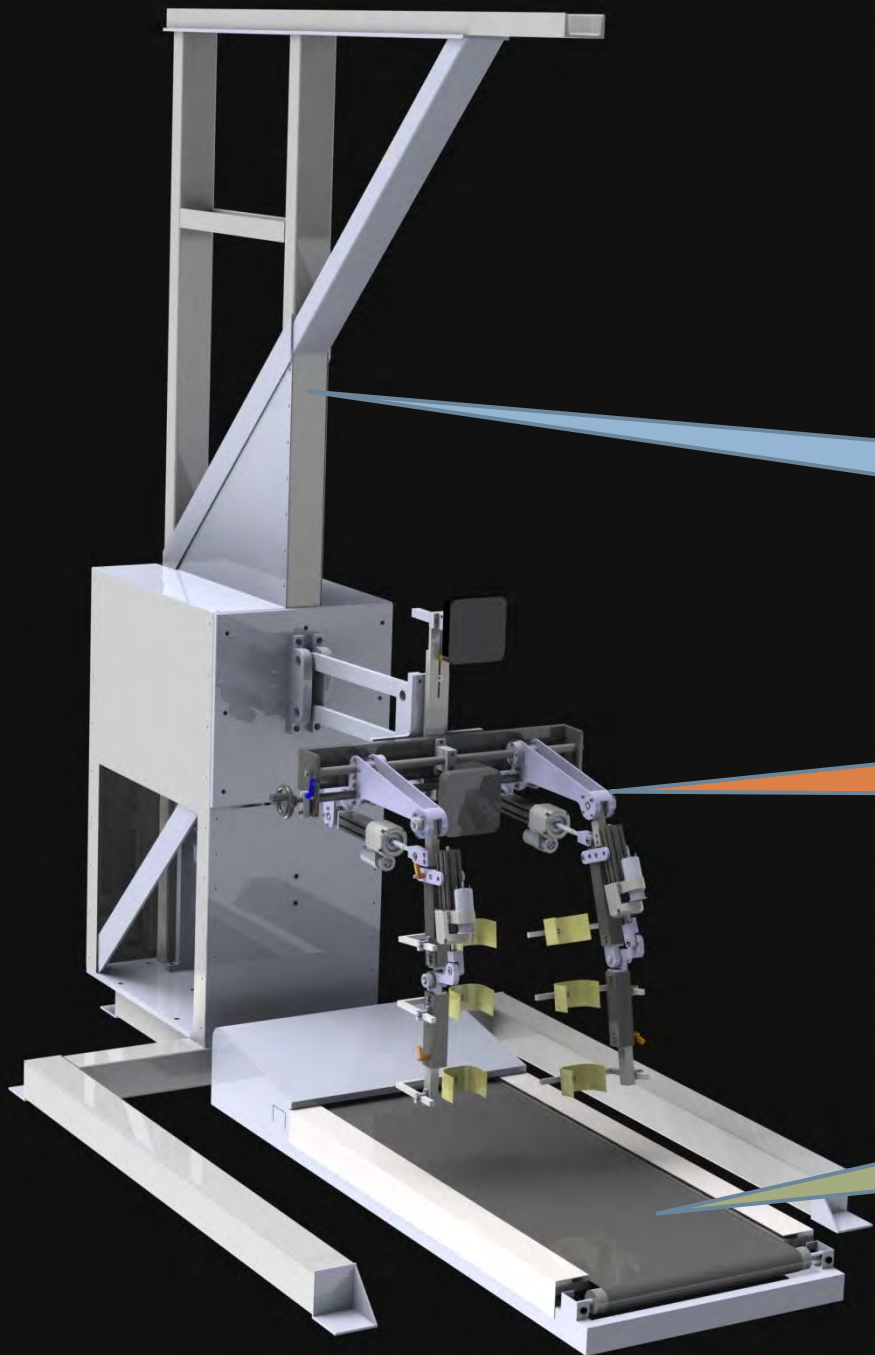
- Expensive (~16 MBaht)
- Closed technology

# Gait Training Machine





# Outline



Patient Weight Compensation  
Device

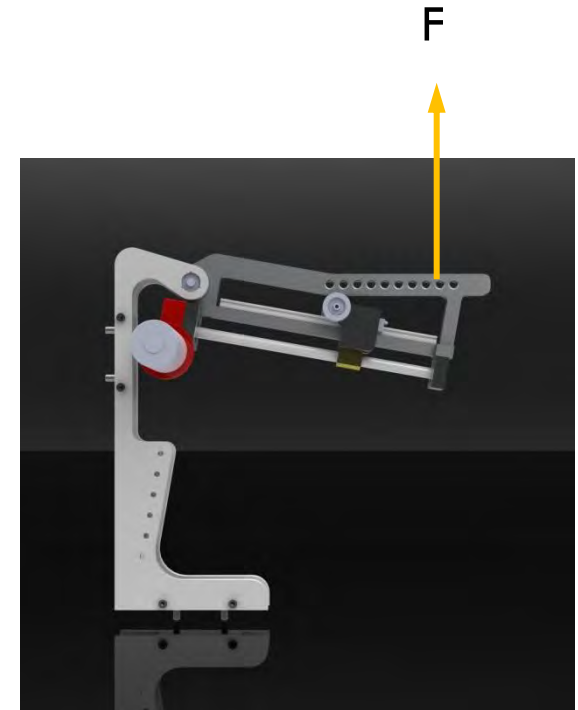
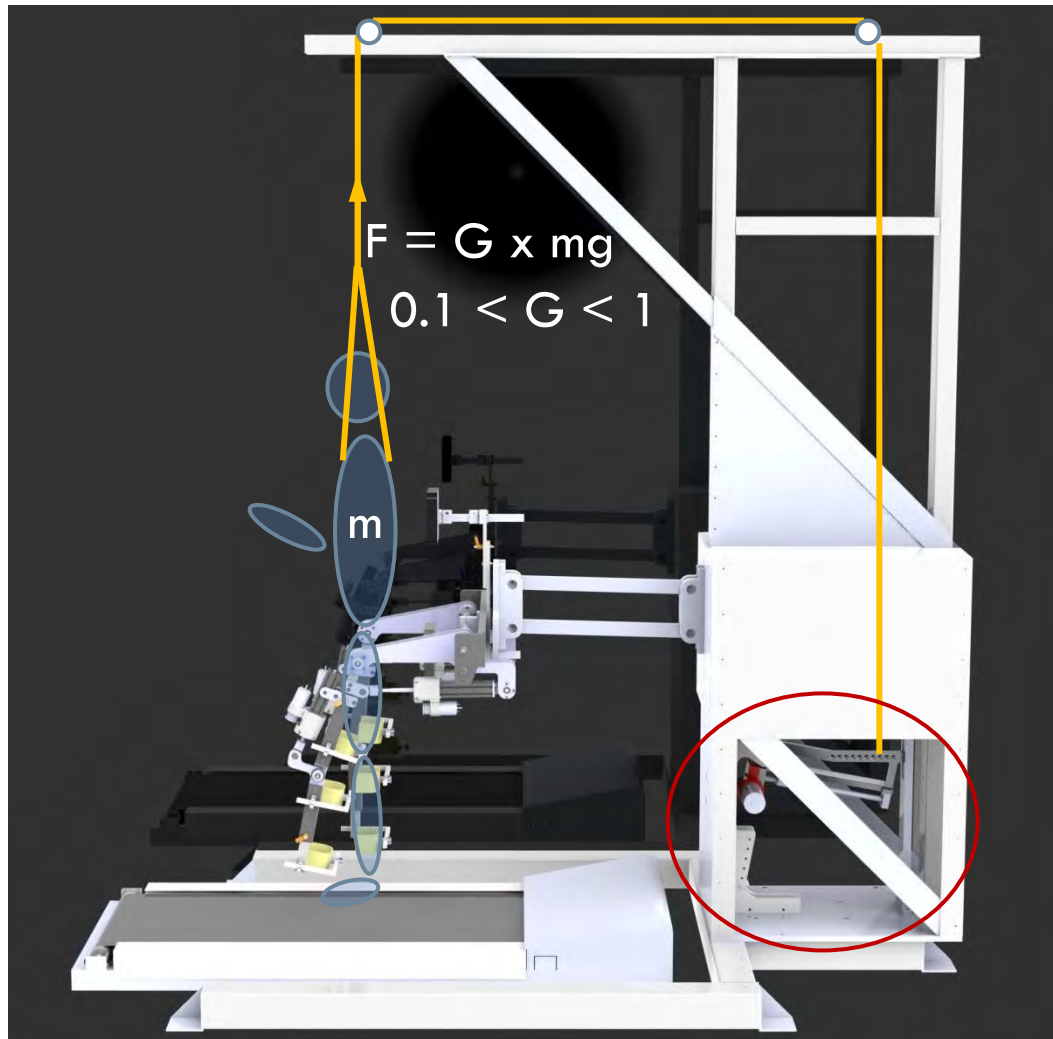
Exoskeleton Robot

Treadmill



# Patient Weight Compensation Device

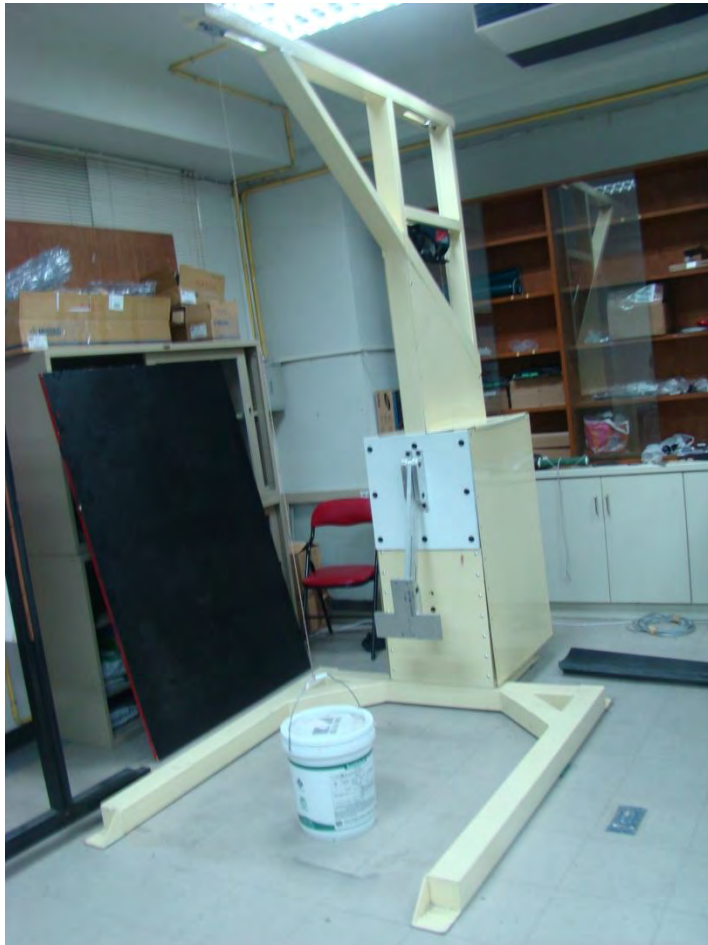
# Patient Weight Compensation Device



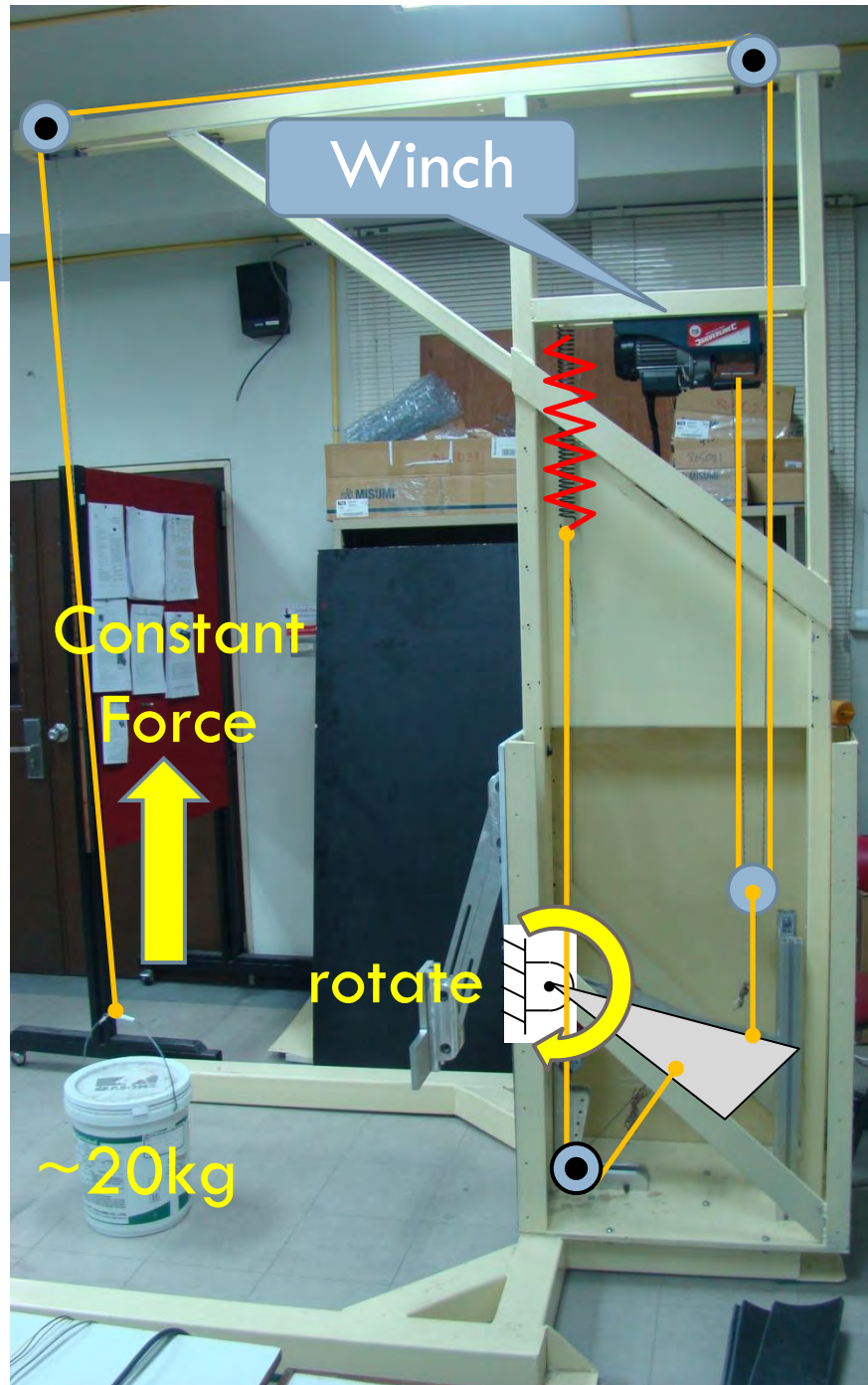
Constant force mechanism

- Completely passive
- Low maintenance

# Patient Weight Compensation Device



# PWD



Constant  
Force

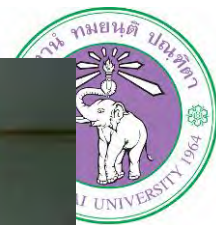
Winch

rotate

~20kg



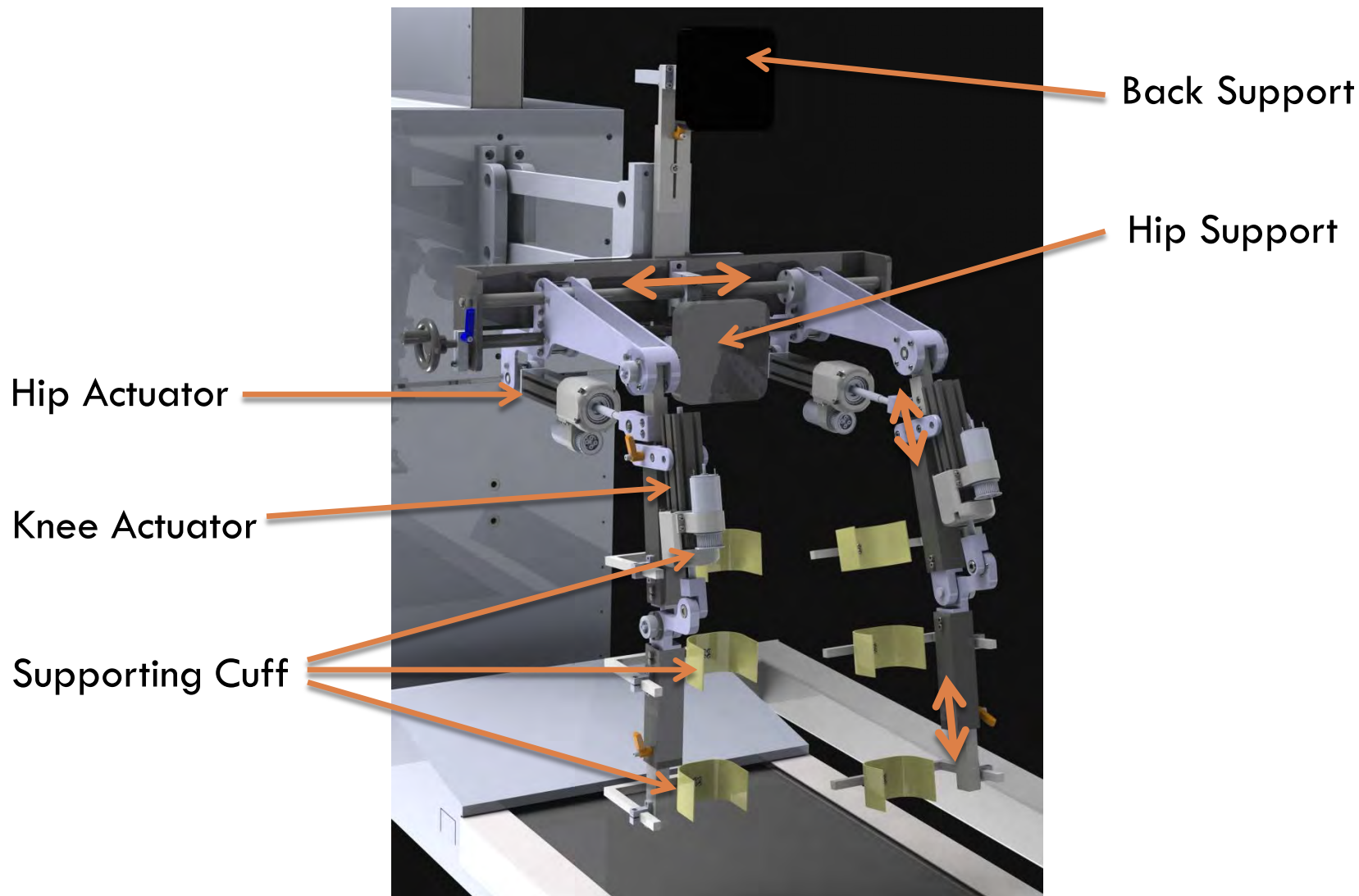
# PWD Demo



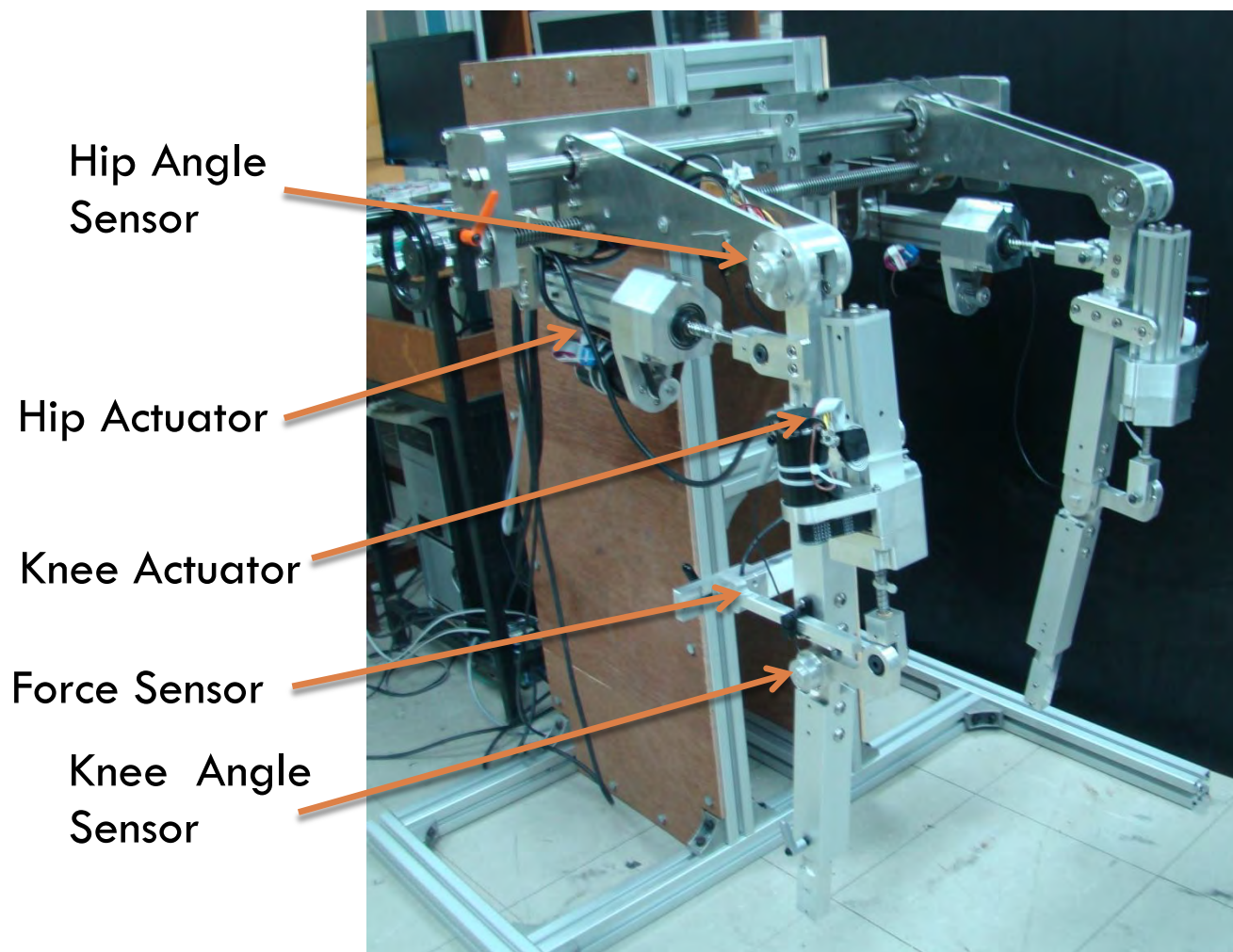


# Exoskeleton Robot

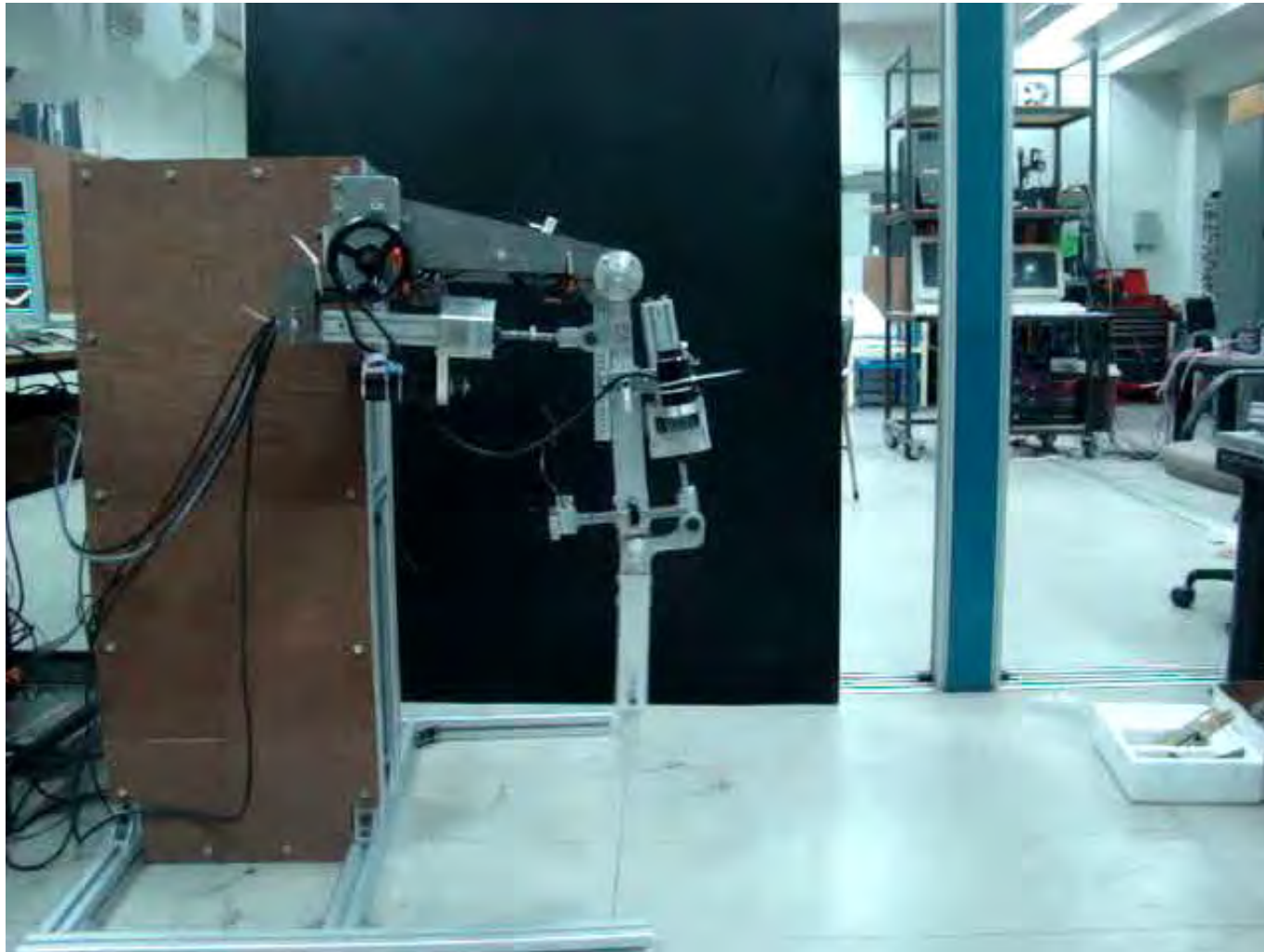
# Exoskeleton Robot



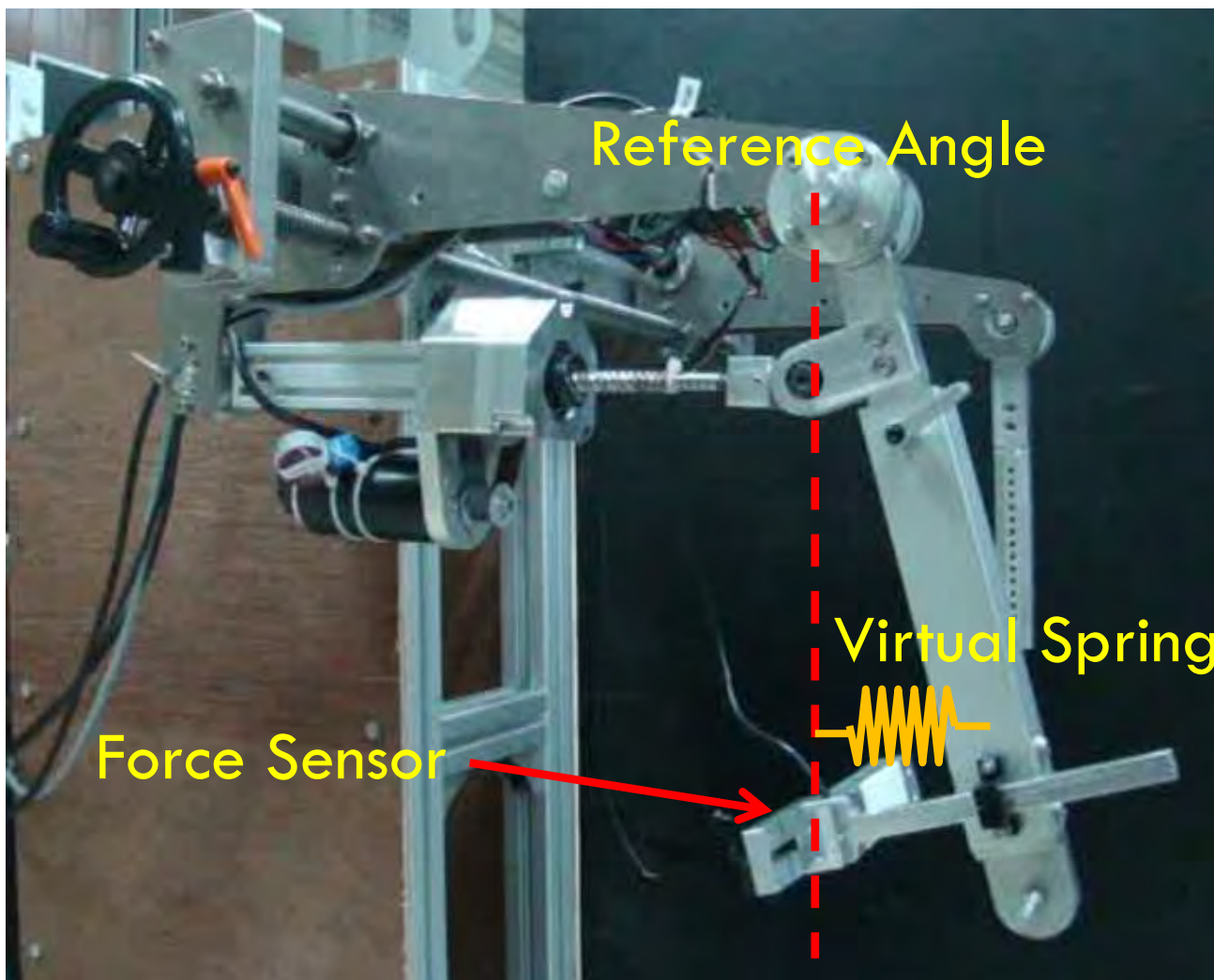
# Exoskeleton Robot



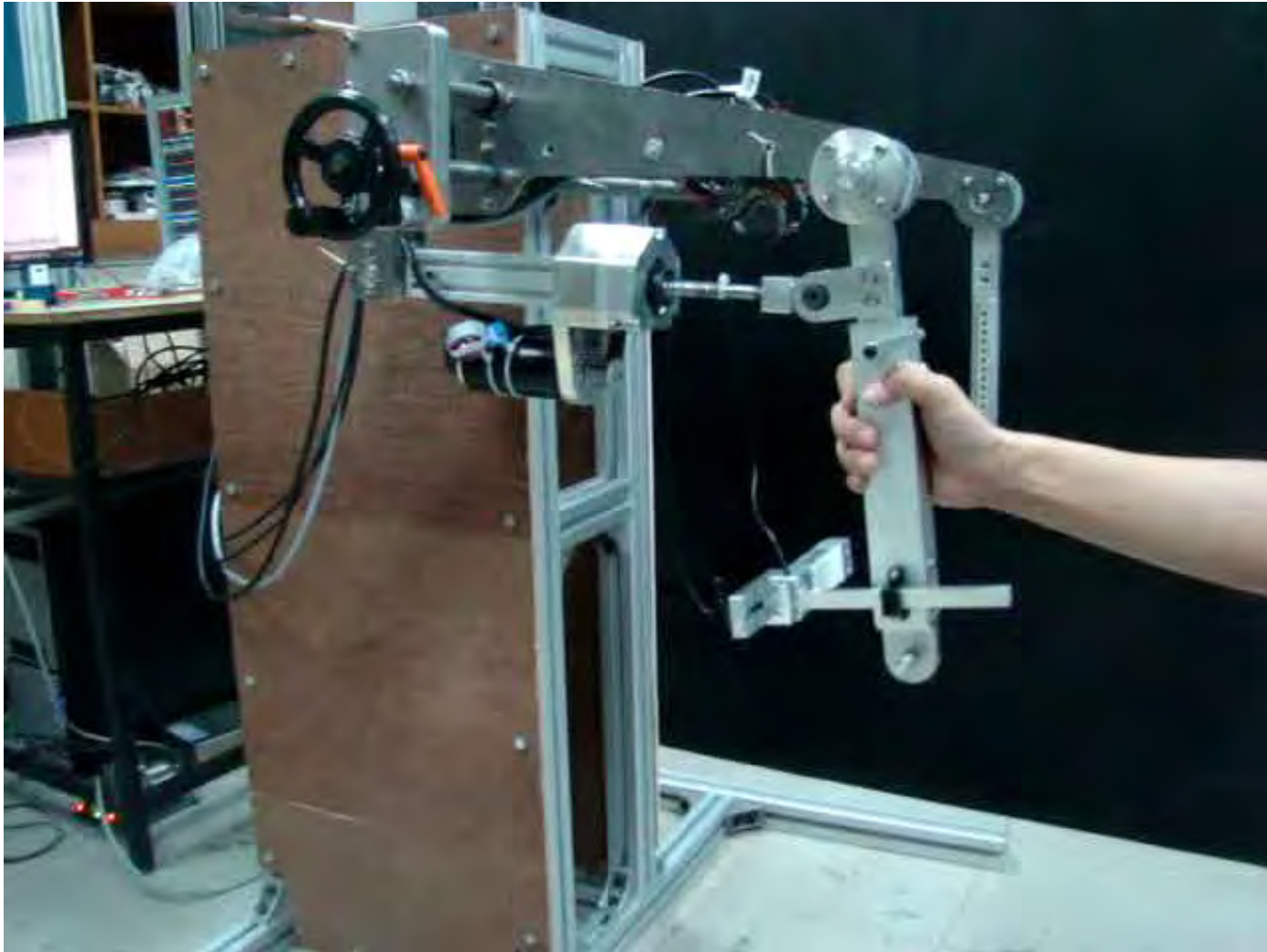
# Exoskeleton Robot Demo



# Impedance Control



# Impedance Control Demo I



# Impedance Control Demo II (Adjusting spring characteristics)

